# Overview

The ultrasonic range sensor uses sound to accurately detect objects and measure distances. This sensor works by sending a sound wave out and calculating the time it takes for the sound wave to get back to the ultrasonic sensor. By doing this, it can tell us how far away objects are relative to the ultrasonic sensor.

Test distance = (high level time \* velocity of sound (340M/S)) / 2 (in meters)

# Step 1: Connect It

Use the following wiring diagram to connect the sensor to your Raspberry Pi



**Important Notes:**

* The wire colors do not matter. Just use whatever is available at your station.
* **Make sure that you are plugging the wires into the correct location on both the Pi and the Sensor (especially the power and ground)**
* The wires move around a lot, so make sure they are firmly in place when you are testing

# Step 2: Code It

We have provided you with a Python code template that can run this sensor/device. The code is located at:

**/home/pi/Documents/rpi-iot-demos/ultrasonic.py**

Use the Geany editor to open this file (NOTE: this will be slow, so be patient). Once it is open, take some time to read the code to see how it works.

Once you are ready, do the following:

1. Find the function called loop().
   1. This function starts when the script runs, and runs forever
2. Modify this function so that it gets the range (using the getDistance() function) and prints it to the console.

def loop():

while True:

distance = getDistance()

print (distance, 'cm')

time.sleep(1.0)

# Step 3: Run / Test It

1. To run the script, open a Linux console and navigate to the folder with your code
   1. Helpful Linux Commands:  
      **ls** lists the contents of the directory  
      **cd <folder\_name>** opens a folder (don’t type the < > characters)  
      **cd ..** exits the folder you are currently in  
      **cd ~** takes you back to your home folder
2. Run the python program by typing the following:

**python3 ultrasonic.py**

1. Try heating up the temperature sensor to see what happens!
   1. If it doesn’t work, make sure that your wiring is correct and that you see lights on the sensor / device
   2. How reliable is this sensor? How far away can an object be to sense it?
   3. Can you write code that tells if an object is coming towards the sensor or going away?
2. **To exit the program, press Ctrl-C in the terminal**